

36V, 8MHz, Precision Low-Noise Operational Amplifier

Features

■ Low Offset Voltage: 25µV (Max.)

■ Low Drift: 0.2µV/°C

Gain Bandwidth Product: 8MHz

■ Wide Supply Range: ±2.25V ~ ±18V

■ Low Quiescent Current: 1.2mA

■ Slew Rate: 2.8V/µs

Unity Gain Stable

Input Over-Voltage Protection

Extended Temperature Ranges
 From -40°C to +125°C

Available in SOP-8 and MSOP-8

Applications

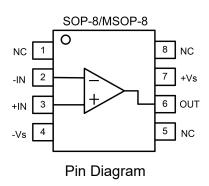
- Sensors and Controls
 Thermocouples
 Resistor thermal detectors (RTDs)
 Strain bridges
 - Shunt current measurements
- Precision Filters
- Data Acquisition
- Medical Instrumentation
- Optical Network Control Circuits
- Wireless Base Station Control Circuits

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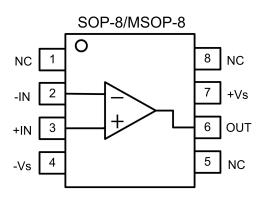
General Description

The COSOP27 is a low power, precision operational amplifier operated on ±2.25V to ±18V supplies. It has very low input offset voltage (25µV) maximum that is obtained by trimming at the wafer stage. These low offset voltages generally eliminate any need for external nulling. COSOP27 also features low input bias current and high open-loop gain. The wide input voltage range of ±13 V minimum combined with a high CMRR of 110dB and high input impedance provide high accuracy in the non-inverting circuit configuration. Excellent linearity and gain accuracy can be maintained even at high closed-loop gains. Stability of offsets and gain with time or variations in temperature is also excellent. The low offset and high open-loop gain make COSOP27 an ideal choice for instrumentation applications.





1. Pin Configuration and Functions



Pin Functions

Name	Description	Note
+Vs	Positive power supply	A bypass capacitor of 0.1µF as close to the part as possible should be placed between power supply pins or between supply pins and ground.
-Vs	Negative power supply or ground	If it is not connected to ground, bypass it with a capacitor of 0.1µF as close to the part as possible.
-IN	Negative input	Inverting input of the amplifier. Voltage range of this pin can go from -Vs to +Vs
+IN	Positive input	Non-inverting input of the amplifier. This pin has the same voltage range as -IN.
OUT	Output	The output voltage range extends to within millivolts of each supply rail.
TRIM	Vos Trim	Optional, place a offset nulling resistor (e.g. $20k\Omega$) between pin 1 & 8
NC	No connection	

2. Package and Ordering Information

					Marking
Model	Channel	Order Number	Package	Package Option	Information
		COSOP27SR/A	SOP-8	Tape and Reel, 4000	COSOP27USR
COSOP27	1	COSOP27SR/B	SOP-8	Tape and Reel, 4000	COSOP27USR
		COSOP27SR/C	SOP-8	Tape and Reel, 4000	COSOP27USR
		COSOP27DT	DIP-8	Tube, 50	COSOP27DT



3. Product Specification

3.1 Absolute Maximum Ratings (1)

Parameter	Rating	Units
Power Supply: +Vs to -Vs	36	V
Differential Input Voltage Range	±0.7	V
Common Mode Input voltage Range ⁽²⁾	-Vs to +Vs	V
Output Current	50	mA
Storage Temperature Range	-65 to 150	°C
Junction Temperature	150	°C
Operating Temperature Range	-40 to 125	°C
ESD Susceptibility, HBM	2000	V

⁽¹⁾ Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

3.2 Thermal Data

Parameter	Rating	Unit
Package Thermal Resistance, R _{θJA} (Juntion-to-ambient)	206 (MSOP8) 155 (SOP8)	°C/W

3.3 Recommended Operating Conditions

Parameter	Rating	Unit
DC Supply Voltage	±2.25V ~ ±18V	V
Input common-mode voltage range	-Vs+2 ~ +Vs-2	V
Operating ambient temperature	-40 to +85	°C

⁽²⁾ Input terminals are diode-clamped to the power-supply rails. Input signals that can swing more than 0.5V beyond the supply rails should be current-limited to 10mA or less.



3.4 Electrical Characteristics

(+V_S=+15V, -V_S=-15V, T_A =+25°C, R_L =10k Ω to V_S /2, unless otherwise noted)

Symbol	Conditions	Min	Тур	Max	Unit
Input Characteristics					
	COSOP27A		±5	±25	
Vos	COSOP27B		±10	±100	μV
	COSOP27C		±20	±200	
ΔV _{OS} /ΔT	-40 to 125°C		0.2	0.7	μV/°C
IB			±4	±8	nA
los			±0.5	±2	nA
V _{CM}		±13	±14		V
CMRR		80	110		dB
AOL	$R_L \ge 2k\Omega$, $V_O = \pm 10V$	90	120		dB
		'		,	
V _{O(PP)}	R _L ≥ 10kΩ	±12	±13.8		V
Isc			±28		mA
				,	
		±2.25		±18	V
PSRR		100	120		dB
IQ			1.2	1.5	mA
	,			1	1
GBWP	C _L =100pF, R _L =10kΩ	5.0	8.0		MHz
SR	C _L =100pF, R _L =10kΩ, Av=1		2.8		V/µs
		'			1
e _n	f=1kHz		5.0		nV/ √ Hz
	Vos ΔVos/ΔT IB Ios VcM CMRR AOL Vo(PP) Isc PSRR IQ GBWP SR	$V_{OS} = \begin{array}{c} COSOP27A \\ COSOP27B \\ COSOP27C \\ \hline \Delta V_{OS}/\Delta T \\ \hline -40 \text{ to } 125^{\circ}C \\ \hline IB \\ \hline Ios \\ \hline V_{CM} \\ \hline CMRR \\ \hline AOL \\ \hline R_{L} \geq 2k\Omega, V_{O} = \pm 10V \\ \hline \\ V_{O(PP)} \\ \hline Isc \\ \hline PSRR \\ \hline I_{Q} \\ \hline \\ GBWP \\ \hline C_{L}=100pF, R_{L}=10k\Omega, Av=1 \\ \hline COSOP27B \\ \hline COSOP27C \\ COSOP27C \\ \hline COSOP27C \\ C$	$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	$V_{OS} = \begin{pmatrix} COSOP27A & \pm 5 \\ COSOP27B & \pm 10 \\ COSOP27C & \pm 20 \\ \Delta V_{OS}/\Delta T & -40 \text{ to } 125^{\circ}C & 0.2 \\ IB & \pm 4 \\ I_{OS} & \pm 0.5 \\ V_{CM} & \pm 13 & \pm 14 \\ CMRR & 80 & 110 \\ AOL & R_{L} \ge 2k\Omega, V_{O} = \pm 10V & 90 & 120 \\ \\ V_{O(PP)} & R_{L} \ge 10k\Omega & \pm 12 & \pm 13.8 \\ I_{SC} & \pm 28 \\ \\ PSRR & 100 & 120 \\ I_{Q} & 1.2 \\ \\ GBWP & C_{L} = 100pF, R_{L} = 10k\Omega, \\ AV = 1 & 50 & 8.0 \\ SR & C_{L} = 100pF, R_{L} = 10k\Omega, \\ AV = 1 & 2.8 \\ \\ C = 100pF, R_{L} = 10k\Omega, \\ C = 100pF, R_{L} = $	$Vos \qquad \begin{array}{c ccccccccccccccccccccccccccccccccccc$



4.0 Application Notes

Driving Capacitive Loads

Driving large capacitive loads can cause stability problems for voltage feedback op amps. As the load capacitance increases, the feedback loop's phase margin decreases, and the closed loop bandwidth is reduced. This produces gain peaking in the frequency response, with overshoot and ringing in the step response. A unity gain buffer (G = +1) is the most sensitive to capacitive loads, but all gains show the same general behavior.

When driving large capacitive loads with these op amps (e.g., > 100 pF when G = +1), a small series resistor at the output (R_{ISO} in Figure 1) improves the feedback loop's phase margin (stability) by making the output load resistive at higher frequencies. It does not, however, improve the bandwidth.

To select $R_{\rm ISO}$, check the frequency response peaking (or step response overshoot) on the bench. If the response is reasonable, you do not need $R_{\rm ISO}$. Otherwise, start $R_{\rm ISO}$ at 1 k Ω and modify its value until the response is reasonable.

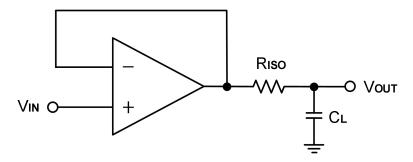


Figure 1. Indirectly Driving Heavy Capacitive Load

An improvement circuit is shown in Figure 2. It provides DC accuracy as well as AC stability. R_F provides the DC accuracy by connecting the inverting signal with the output, C_F and R_{ISO} serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop.

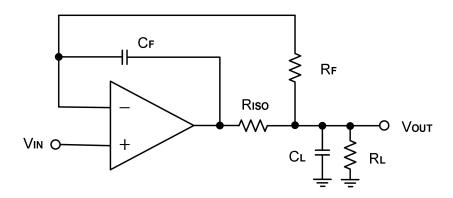


Figure 2. Indirectly Driving Heavy Capacitive Load with DC Accuracy



For noninverting configuration, there are two others ways to increase the phase margin: (a) by increasing the amplifier's gain or (b) by placing a capacitor in parallel with the feedback resistor to counteract the parasitic capacitance associated with inverting node, as shown in Figure 3.

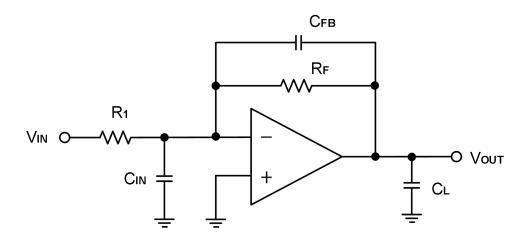


Figure 3. Adding a Feedback Capacitor in the Noninverting Configuration

Power-Supply Bypassing and Layout

The COSOP27 operates from a single +4.5V to +36V supply or dual ± 2.25 V to ± 18 V supplies. For single-supply operation, bypass the power supply +Vs with a $0.1\mu F$ ceramic capacitor which should be placed close to the +Vs pin. For dual-supply operation, both the +Vs and the -Vs supplies should be bypassed to ground with separate $0.1\mu F$ ceramic capacitors. $2.2\mu F$ tantalum capacitor can be added for better performance.

The length of the current path is directly proportional to the magnitude of parasitic inductances and thus the high frequency impedance of the path. High speed currents in an inductive ground return create an unwanted voltage noise. Broad ground plane areas will reduce the parasitic inductance. Thus a ground plane layer is important for high speed circuit design.

Typical Application Circuits

Differential Amplifier

The circuit shown in Figure 4 performs the differential function. If the resistors ratios are equal $(R_4 / R_3 = R_2 / R_1)$, then $V_{OUT} = (V_{IP} - V_{IN}) \times R_2 / R_1 + V_{REF}$.



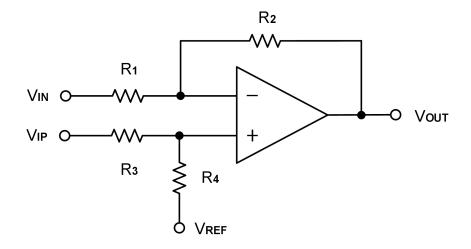


Figure 4. Differential Amplifier

Low Pass Active Filter

When receiving low-level signals, limiting the bandwidth of the incoming signals into the system is often required. The simplest way to establish this limited bandwidth is to place an RC filter at the noninverting terminal of the amplifier. If even more attenuation is needed, a multiple pole filter is required. The Sallen-Key filter can be used for this task, as Figure 5. For best results, the amplifier should have a bandwidth that is 8 to 10 times the filter frequency bandwidth. Failure to follow this guideline can result in reduction of phase margin. The large values of feedback resistors can couple with parasitic capacitance and cause undesired effects such as ringing or oscillation in high-speed amplifiers. Keep resistors value as low as possible and consistent with output loading consideration.

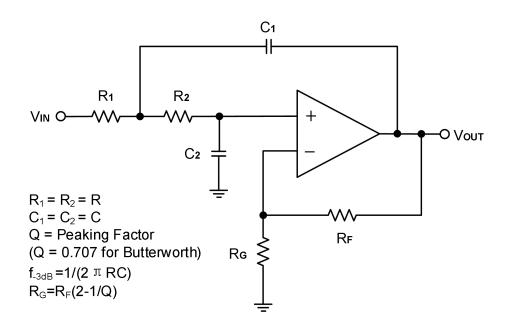
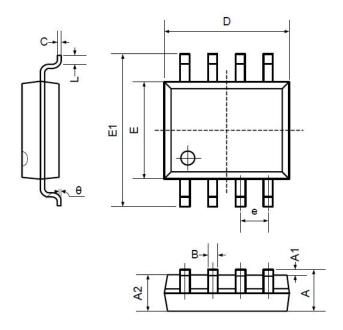


Figure 5. Two-Pole Low-Pass Sallen-Key Active Filter



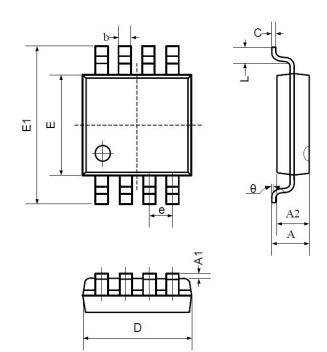
5. Package Information

5.1 SOP8 (Package Outline Dimensions)



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
Α	1.350	1.750	0.053	0.069
A1	0.100	0.250	0.004	0.010
A2	1.350	1.550	0.053	0.061
В	0.330	0.510	0.013	0.020
С	0.190	0.250	0.007	0.010
D	4.780	5.000	0.188	0.197
E	3.800	4.000	0.150	0.157
E1	5.800	6.300	0.228	0.248
е	1.270TYP		0.050TYP	
L	0.400	1.270	0.016	0.050
θ	0°	8°	0°	8°

5.2 MSOP8 (Package Outline Dimensions)



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
Α	0.800	1.200	0.031	0.047
A1	0.000	0.200	0.000	0.008
A2	0.760	0.970	0.030	0.038
b	0.30 TYP		0.012 TYP	
С	0.15 TYP		0.006 TYP	
D	2.900	3.100	0.114	0.122
е	0.65 TYP		0.026 TYP	
E	2.900	3.100	0.114	0.122
E1	4.700	5.100	0.185	0.201
L	0.410	0.650	0.016	0.026
θ	0° 6°		0°	6°